

Citizenship: Canada, Netherlands

CONTACT  
INFORMATION

**Work address:**  
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University of British Columbia  
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EDUCATION AND  
ACADEMIC POSITIONS

UNIVERSITY OF BRITISH COLUMBIA 2018-Present  
**Assistant Professor**  
Department of Statistics

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2016-2018  
**Postdoctoral Associate**  
Computer Science and Artificial Intelligence Laboratory (CSAIL)  
Institute for Data, Systems, and Society (IDSS)  
Supervisor: Professor Tamara Broderick  
Research Focus: automated, scalable Bayesian inference; Bayesian nonparametrics; exchangeability; streaming data

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2013-2016  
**Doctor of Philosophy (Ph.D.), Machine Learning and Statistics**  
Laboratory for Information and Decision Systems (LIDS)  
Supervisor: Professor Jonathan P. How  
Thesis Title: Truncated Bayesian Nonparametrics  
Cumulative GPA: 5.0/5.0

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2011-2013  
**Master of Science (S.M.), Aeronautics and Astronautics**  
Laboratory for Information and Decision Systems (LIDS)  
Supervisor: Professor Jonathan P. How  
Thesis Title: Multiagent Planning with Bayesian Nonparametric Asymptotics  
Cumulative GPA: 5.0/5.0

UNIVERSITY OF TORONTO 2007-2011  
**Bachelor of Applied Science (B.A.Sc.), Engineering Science, Honours with High Distinction**  
Major in Aerospace Engineering  
Cumulative GPA: 3.93/4.0

PUBLICATIONS

SUBMITTED FOR REVIEW

- **T. Campbell**, T. Broderick. “Automated scalable Bayesian inference via Hilbert coresets.” Available at arXiv:1710.05053.
- **T. Campbell**, D. Cai, T. Broderick. “Exchangeable trait allocations.” Available at arXiv:1609.09147.

REFEREED PUBLICATIONS

- **T. Campbell**, T. Broderick. “Bayesian coreset construction via greedy iterative geodesic ascent.” International Conference on Machine Learning, 2018. (**long oral, 12%**)
- **T. Campbell\***, J. Huggins\*, J. How, T. Broderick. “Truncated random measures.” Bernoulli (accepted). Available at arXiv:1603.00861.
- **T. Campbell**, B. Kulis and J. P. How. “Dynamic clustering algorithms via small-variance analysis of the Markov dependent Dirichlet process.” IEEE Transactions on Pattern Analysis and Machine Intelligence (accepted). Available at arXiv:1707.08493.
- J. Straub\*, **T. Campbell\***, J. P. How, J. W. Fisher III. “Efficient global point cloud alignment using Bayesian nonparametric mixtures.” IEEE Conference on Computer Vision and Pattern Recognition, 2017. (**spotlight, 8% acceptance**)
- J. Huggins, **T. Campbell**, T. Broderick. “Coresets for scalable Bayesian logistic regression.” Advances in Neural Information Processing Systems, 2016 (**22% acceptance**).
- D. Cai, **T. Campbell**, T. Broderick. “Edge-exchangeable graphs and sparsity.” Advances in Neural Information Processing Systems, 2016 (**22% acceptance**).
- **T. Campbell**, J. Straub, J. W. Fisher III, and J. P. How. “Streaming, massively parallel variational inference for Bayesian nonparametrics.” Advances in Neural Information Processing Systems, 2015 (**22% acceptance**).
- J. Straub, **T. Campbell**, J. P. How and J. W. Fisher III. “Small-variance nonparametric clustering on the hypersphere.” IEEE Conference on Computer Vision and Pattern Recognition, 2015. (**oral, 3% acceptance**)
- **T. Campbell** and J. P. How. “Bayesian nonparametric set construction for robust optimization.” American Control Conference, 2015.
- **T. Campbell** and J. P. How. “Approximate decentralized Bayesian inference.” Uncertainty in Artificial Intelligence, 2014. (**32% acceptance**)

- **T. Campbell**, M. Liu, B. Kulis, J. P. How, and L. Carin. “Dynamic clustering via asymptotics of the dependent Dirichlet process mixture.” Advances in Neural Information Processing Systems, 2013. **(25% acceptance)**
- **T. Campbell**, L. Johnson and J. P. How. “Multiagent allocation of Markov decision process tasks.” American Control Conference, 2013.
- **T. Campbell**, R. H. Klein, A. Geramifard and J. P. How. “Simultaneous clustering on representation expansion for learning multimodel MDPs.” Reinforcement Learning and Decision Making, 2013.

#### BOOK REVIEWS AND DISCUSSIONS

- **T. Campbell**, T. Broderick. Discussion of “Sparse graphs using exchangeable random measures.” Journal of the Royal Statistical Society B, 79:5, 1295–1366, 2017.
- **T. Campbell**, T. Broderick. Review of “Handbook of mixed membership models and their applications.” Book Reviews, Journal of the American Statistical Association, 111:516, 1840–1851, 2016.

#### IN THE NEWS

- MIT front page, July 2014. “Collaborative Learning – for Robots.”  
Online: <http://newsoffice.mit.edu/2014/collaborative-learning-for-robots-0625>
- Popular Science, July 2014: “Collaborative Algorithm Lets Autonomous Robots Team Up and Learn From Each Other.” Online: <http://www.popsci.com/blog-network/zero-moment/collaborative-algorithm-lets-autonomous-robots-team-and-learn-each-other>

#### HONORS & INVITED TALKS

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#### MASSACHUSETTS INSTITUTE OF TECHNOLOGY

- 2018 Allerton Invited Talk
- 2018 JSM Invited Talk on Bayesian Coresets (Upcoming)
- 2018 Boston Bayesians Invited Talk
- 2017 BIRS Invited Talk on Bayesian Coresets
- 2017 BNP Invited Talk on Exchangeable Trait Allocations
- 2016 SBSS Student Paper Award
- 2012 GNC Best Presentation in Session
- 2011 Natural Science and Engineering Research Council of Canada PGS-M Research Fellowship

#### UNIVERSITY OF TORONTO

- 2011 James D. Todd Memorial Scholarship
- 2010 Kenneth Sullivan / Pratt Whitney Canada Scholarship
- 2009 Natural Science and Engineering Research Council of Canada Undergraduate Summer Research Award
- 2008 Engineering Science Research Opportunity Program Scholarship
- 2007 Faculty of Applied Science and Engineering Admissions Scholarship

#### PROFESSIONAL SERVICE

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#### REVIEWER

- Neural Information Processing Systems (NIPS)
- Artificial Intelligence and Statistics (AISTATS)
- International Conference on Machine Learning (ICML)
- Journal of Neurocomputing
- Journal of Aerospace Information Systems (JAIS)
- American Controls Conference (ACC)
- AIAA Conference on Guidance, Navigation and Control (GNC)
- International Conference on Intelligent Robots and Systems (IROS)
- Computational Statistics and Data Analysis (CSDA)
- Journal of Machine Learning Research (JMLR)
- NIPS 2016 Workshop on Advances in Approximate Bayesian Inference
- NIPS 2015 Workshop on Advances in Approximate Bayesian Inference

#### ORGANIZING COMMITTEES

- NIPS 2016 Workshop on Practical Bayesian Nonparametrics
- NIPS 2015 Workshop on Bayesian Nonparametrics: The Next Generation

#### AWARD COMMITTEES

- 2017 SBSS Student Paper Award Committee
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PREVIOUS RESEARCH  
EXPERIENCE

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

2011-2016

**Doctoral Research**

Supervisor: Professor Jonathan P. How

Research focused on statistical inference and approximations for Bayesian nonparametric models with streaming, distributed data. Major research contributions include truncated approximations for normalized and unnormalized completely random measures, approximate variational techniques for both parametric and nonparametric streaming, distributed inference, fast low-variance asymptotic Bayesian nonparametric clustering algorithms, and statistically-designed uncertainty sets for robust linear optimization.

UNIVERSITY OF TORONTO INSTITUTE FOR AEROSPACE STUDIES

Spring 2011

**Undergraduate Thesis Research**

Supervisor: Professor Phillippe Lavoie

Research focused on dielectric barrier discharge plasma actuators for flow control over airfoils. Created computational engine for simulating the creation, absorption and transport processes of the plasma that occurs around the actuators. Developed a new initial condition for plasma actuator simulations based on solutions of the Laplace equation on a rectangular domain, with a focus on optimizing the relaxation time of such simulations.

UNIVERSITY OF TORONTO INSTITUTE FOR AEROSPACE STUDIES

Summer 2009

**Summer Research Project**

Supervisor: Professor Timothy Barfoot

Research focused on the use of LiDAR intensity images for lighting-invariant vision-based localization in mobile robotics. Created a 3D odometry package for the research group using data from wheel odometry sensors and an inertial measurement unit. Ran experiments in decentralized state estimation of groups of robots, laser ranger point cloud stitching, and optimization of next viewpoint for environment mapping.

UNIVERSITY OF TORONTO DEPARTMENT OF PHYSICS

Summer 2008

**Summer Research Project**

Supervisor: Professor Henry van Driel

Research focused on surface plasmon polaritons on gold and silver surface gratings. Programmed a finite difference time domain computational simulation engine for Maxwell's equations in 2D environments.

TEACHING  
EXPERIENCE

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

- Spring 2017 – 6.882 Bayesian Modeling and Inference (6.7/7 overall rating)
- Spring 2017 – A Whirlwind Tour of ML: Bayesian Methods

UNIVERSITY OF TORONTO

- 2009-2010 – Facilitated Study Group Leader for Circuit Analysis (ECE150) and Computer Programming (CSC192)

OTHER RELEVANT  
EXPERIENCE

PDT PARTNERS, LLC

Summer 2015

**Summer Research Associate**

Conducted quantitative market research.

HILL & SCHUMACHER PATENT & TRADEMARK AGENTS

Summers 2010-2011

**Assistant Patent Agent**

Supervisors: Lynn Schumacher, Ph.D. and Nancy Hill, LL.B.

Performed all aspects of patent prosecution. Under the supervision of two patent agents, met with clients to discuss their inventions, drafted full patent applications, provisionals, divisionals, continuations-in-part, and Patent Cooperation Treaty (PCT) applications for those inventions, and responded to office actions from the government. Performed these duties for Canadian, American, European, and Japanese jurisdictions.

UNIVERSITY OF TORONTO BLUE SKY SOLAR CAR RACING TEAM

2009-2010

**Mechanical Systems Co-Director**

Designed the suspension system and supervised the design of the braking system, roll cage, wheel rims, and steering system for the solar car.

AER201: ENGINEERING DESIGN

2009

**Electrical Systems Designer**

Designed and built the electrical system of a candy vending machine robot. The system contained a microprocessor, display, dispenser motors, infrared sensor circuits, and fail-safe battery backup. The system dispensed 4 types of candy and sensed when the correct number had been dispensed.

COURSEWORK &  
ADDITIONAL SKILLS

**Inference and Learning:** Fundamentals of Probability Theory, Algorithms for Inference, Theoretical Statistics, Probability and Statistics, Stochastic Estimation

**Optimization:** Nonlinear Programming, Combinatorial Optimization, Robust Optimization, Scientific Computing

**Control and Decision Making:** Classical Control Systems, State-Space Control Systems, Principles of Optimal Control, Stochastic Control, Principles of Autonomy and Decision Making

**Mathematics:** Calculus, Vector Calculus, Ordinary Differential Equations, Partial Differential Equations, Complex Analysis, Real Analysis, Functional Analysis, Linear Algebra, Abstract Algebra

**Programming:** C/C++ (13y), Python (6y), Java (7y), MATLAB (7y), L<sup>A</sup>T<sub>E</sub>X(7y), SVN/Git (7y)

**Robotics:** Electrical design, mechanical design, microcontroller programming, soldering (10y). Platforms: Pioneer 3-AT, Robosoft RobuROC 6, iRobot Create

**Intellectual Property:** Drafting patent applications and all other aspects of prosecution, including responding to office actions, for Canada, the United States, Europe, and Japan (2y)