

Citizenship: Canada, Netherlands

CONTACT
INFORMATION

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EDUCATION AND
ACADEMIC POSITIONS

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2016-present
Postdoctoral Associate, Computer Science and Artificial Intelligence Laboratory (CSAIL)
Supervisor: Professor Tamara Broderick
Research Focus: Bayesian nonparametrics; exchangeability; streaming, distributed inference

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2013-2016
Doctor of Philosophy (Ph.D.), Machine Learning and Statistics
Laboratory for Information and Decision Systems (LIDS)
Supervisor: Professor Jonathan P. How
Thesis Title: Truncated Bayesian Nonparametrics
Cumulative GPA: 5.0/5.0

MASSACHUSETTS INSTITUTE OF TECHNOLOGY 2011-2013
Master of Science (S.M.), Aeronautics and Astronautics
Laboratory for Information and Decision Systems (LIDS)
Supervisor: Professor Jonathan P. How
Thesis Title: Multiagent Planning with Bayesian Nonparametric Asymptotics
Cumulative GPA: 5.0/5.0

UNIVERSITY OF TORONTO 2007-2011
Bachelor of Applied Science (B.A.Sc.), Engineering Science, Honours with High Distinction
Major in Aerospace Engineering
Cumulative GPA: 3.93/4.0

PUBLICATIONS

REFEREED PUBLICATIONS

- J. Straub*, **T. Campbell***, J. P. How, J. W. Fisher III. “Efficient global point cloud alignment using Bayesian nonparametric mixtures”. IEEE Conference on Computer Vision and Pattern Recognition, 2017. (**spotlight, 8% acceptance**)
- J. Huggins, **T. Campbell**, T. Broderick. “Coresets for scalable Bayesian logistic regression”. Advances in Neural Information Processing Systems, 2016 (**22% acceptance**).
- D. Cai, **T. Campbell**, T. Broderick. “Edge-exchangeable graphs and sparsity.” Advances in Neural Information Processing Systems, 2016 (**22% acceptance**).
- **T. Campbell**, J. Straub, J. W. Fisher III, and J. P. How. “Streaming, massively parallel variational inference for Bayesian nonparametrics”. Advances in Neural Information Processing Systems, 2015 (**22% acceptance**).
- J. Straub, **T. Campbell**, J. P. How and J. W. Fisher III. “Small-variance nonparametric clustering on the hypersphere”. IEEE Conference on Computer Vision and Pattern Recognition, 2015. (**oral, 3% acceptance**)
- **T. Campbell** and J. P. How. “Bayesian nonparametric set construction for robust optimization”. American Control Conference, 2015.
- **T. Campbell** and J. P. How. “Approximate decentralized Bayesian inference”. Uncertainty in Artificial Intelligence, 2014. (**32% acceptance**)
- **T. Campbell**, M. Liu, B. Kulis, L. Carin and J. P. How. “Dynamic clustering via asymptotics of the dependent Dirichlet process mixture”. Advances in Neural Information Processing Systems, 2013. (**25% acceptance**)
- **T. Campbell**, L. Johnson and J. P. How. “Multiagent allocation of Markov decision process tasks”. American Control Conference, 2013.
- **T. Campbell**, R. H. Klein, A. Geramifard and J. P. How. “Simultaneous clustering on representation expansion for learning multimodel MDPs”. Reinforcement Learning and Decision Making, 2013.

SUBMITTED FOR REVIEW

- **T. Campbell**, D. Cai, T. Broderick. “Exchangeable trait allocations”. Available at arXiv:1609.09147.
- **T. Campbell***, J. Huggins*, J. How, T. Broderick. “Truncated Random Measures”. Available at arXiv:1603.00861.
- **T. Campbell**, B. Kulis and J. P. How. “Dynamic Clustering Algorithms via Small-Variance Analysis of the Markov Dependent Dirichlet Process”. 2016 (submitted).

BOOK REVIEWS

- **T. Campbell**, T. Broderick. Review of “Handbook of mixed membership models and their applications”. Book Reviews, Journal of the American Statistical Association, 111:516, 1840–1851, 2016.

IN THE NEWS

- MIT front page, July 2014. “Collaborative Learning – for Robots”.
Online: <http://newsoffice.mit.edu/2014/collaborative-learning-for-robots-0625>
- Popular Science, July 2014: “Collaborative Algorithm Lets Autonomous Robots Team Up and Learn From Each Other”. Online: <http://www.popsoci.com/blog-network/zero-moment/collaborative-algorithm-lets-autonomous-robots-team-and-learn-each-other>

HONORS & INVITED TALKS

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

- 2018 JSM Invited Talk on Bayesian Coresets (Invited)
- 2017 BIRS Invited Talk on Bayesian Coresets (Upcoming)
- 2017 BNP Invited Talk on Exchangeable Trait Allocations
- 2016 SBSS Student Paper Award
- 2012 GNC Best Presentation in Session
- 2011 Natural Science and Engineering Research Council of Canada PGS-M Research Fellowship

UNIVERSITY OF TORONTO

- 2011 James D. Todd Memorial Scholarship
- 2010 Kenneth Sullivan / Pratt Whitney Canada Scholarship
- 2009 Natural Science and Engineering Research Council of Canada Undergraduate Summer Research Award
- 2008 Engineering Science Research Opportunity Program Scholarship
- 2007 Faculty of Applied Science and Engineering Admissions Scholarship

PROFESSIONAL SERVICE

REVIEWER

- Neural Information Processing Systems (NIPS)
- Artificial Intelligence and Statistics (AISTATS)
- International Conference on Machine Learning (ICML)
- Journal of Neurocomputing
- Journal of Aerospace Information Systems (JAIS)
- American Controls Conference (ACC)
- AIAA Conference on Guidance, Navigation and Control (GNC)
- International Conference on Intelligent Robots and Systems (IROS)

PROGRAM & ORGANIZING COMMITTEES

- NIPS 2016 Workshop on Advances in Approximate Bayesian Inference
- NIPS 2016 Workshop on Practical Bayesian Nonparametrics
- NIPS 2015 Workshop on Advances in Approximate Bayesian Inference
- NIPS 2015 Workshop on Bayesian Nonparametrics: The Next Generation

AWARD COMMITTEES

- 2017 SBSS Student Paper Award Committee

PREVIOUS RESEARCH EXPERIENCE

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

2011-2016

Doctoral Research

Supervisor: Professor Jonathan P. How

Research focused on statistical inference and approximations for Bayesian nonparametric models with streaming, distributed data. Major research contributions include truncated approximations for normalized and unnormalized completely random measures, approximate variational techniques for both parametric and nonparametric streaming, distributed inference, fast low-variance asymptotic Bayesian nonparametric clustering algorithms, and statistically-designed uncertainty sets for robust linear optimization.

UNIVERSITY OF TORONTO INSTITUTE FOR AEROSPACE STUDIES

Spring 2011

Undergraduate Thesis Research

Supervisor: Professor Phillippe Lavoie

Research focused on dielectric barrier discharge plasma actuators for flow control over airfoils. Created computational engine for simulating the creation, absorption and transport processes of the plasma that occurs around the actuators. Developed a new initial condition for plasma actuator simulations based on solutions of the Laplace equation on a rectangular domain, with a focus on optimizing the relaxation time of such simulations.

Summer Research Project

Supervisor: Professor Timothy Barfoot

Research focused on the use of LiDAR intensity images for lighting-invariant vision-based localization in mobile robotics. Created a 3D odometry package for the research group using data from wheel odometry sensors and an inertial measurement unit. Ran experiments in decentralized state estimation of groups of robots, laser ranger point cloud stitching, and optimization of next viewpoint for environment mapping.

UNIVERSITY OF TORONTO DEPARTMENT OF PHYSICS

Summer 2008

Summer Research Project

Supervisor: Professor Henry van Driel

Research focused on surface plasmon polaritons on gold and silver surface gratings. Programmed a finite difference time domain computational simulation engine for Maxwell's equations in 2D environments.

TEACHING
EXPERIENCE

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

- Spring 2017 – 6.882 Bayesian Modeling and Inference (6.7/7 overall rating from 15 students)
- Spring 2017 – A Whirlwind Tour of ML: Bayesian Methods

UNIVERSITY OF TORONTO

- Spring 2010 – Facilitated Study Group Leader

OTHER RELEVANT
EXPERIENCE

PDT PARTNERS, LLC

Summer 2015

Summer Research Associate

Conducted quantitative market research.

HILL & SCHUMACHER PATENT & TRADEMARK AGENTS

Summers 2010-2011

Assistant Patent Agent

Supervisors: Lynn Schumacher, Ph.D. and Nancy Hill, LL.B.

Performed all aspects of patent prosecution. Under the supervision of two patent agents, met with clients to discuss their inventions, drafted full patent applications, provisionals, divisionals, continuations-in-part, and Patent Cooperation Treaty (PCT) applications for those inventions, and responded to office actions from the government. Performed these duties for Canadian, American, European, and Japanese jurisdictions.

UNIVERSITY OF TORONTO BLUE SKY SOLAR CAR RACING TEAM

2009-2010

Mechanical Systems Co-Director

Designed the suspension system and supervised the design of the braking system, roll cage, wheel rims, and steering system for the solar car.

AER201: ENGINEERING DESIGN

2009

Electrical Systems Designer

Designed and built the electrical system of a candy vending machine robot. The system contained a microprocessor, display, dispenser motors, infrared sensor circuits, and fail-safe battery backup. The system dispensed 4 types of candy and sensed when the correct number had been dispensed.

UNIVERSITY OF TORONTO

2009-2010

Facilitated Learning Group Leader

Ran tutorial sessions in Circuit Analysis (ECE150) and Advanced Computer Programming (CSC192) for students in Engineering Science.

COURSEWORK

Inference and Learning: Fundamentals of Probability Theory, Algorithms for Inference, Theoretical Statistics, Probability and Statistics, Stochastic Estimation

Optimization: Nonlinear Programming, Combinatorial Optimization, Robust Optimization, Scientific Computing

Control and Decision Making: Classical Control Systems, State-Space Control Systems, Principles of Optimal Control, Stochastic Control, Principles of Autonomy and Decision Making

Mathematics: Calculus, Vector Calculus, Ordinary Differential Equations, Partial Differential Equations, Complex Analysis, Real Analysis, Functional Analysis, Linear Algebra, Abstract Algebra

ADDITIONAL
SKILLS

Programming: C/C++ (12 years), Python (5 years), Java (7 years), MATLAB (7 years), L^AT_EX(6 years), SVN/Git (5 years)

Robotics: Electrical design, mechanical design, microcontroller programming, soldering (10 years). Platforms: Pioneer 3-AT, Robosoft RobuROC 6, iRobot Create

Intellectual Property: Drafting patent applications and all other aspects of prosecution, including responding to office actions, for Canada, the United States, Europe, and Japan (2 summers)

REFERENCES

Tamara Broderick

ITT Career Development Assistant Professor
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Jonathan P. How

Richard C. Maclaurin Professor of Aeronautics and Astronautics
Director of the Aerospace Controls Laboratory
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John W. Fisher III

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